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## Revision History

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<th>Rev</th>
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<tr>
<td>0.1</td>
<td>9/2/2013</td>
<td>Per Larsson</td>
<td>First draft</td>
</tr>
<tr>
<td>0.2</td>
<td>11/10/2013</td>
<td>Per Larsson</td>
<td>Added sections Acknowledgements and Language. Added reference section on waitsig(). Updated reference section on print() and pltbutils_clkgen.</td>
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<tr>
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<td>Per Larsson</td>
<td>Added sections User Configuration, Configuring Simulation Halt, Configuring Messages for Integration Environments. In reference section added starttest, endtest, removed testname. Updated figures and feature bullets.</td>
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<td>Per Larsson</td>
<td>Updates for alpha0006: Text modified in numerous places to reflect that PlTbUtils is now using the variable pltbv and the signal pltbs for control and status, instead of the previous shared variable and global signals.</td>
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<tr>
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<td>13/1/2014</td>
<td>Per Larsson</td>
<td>Updates for alpha0007: added example testbench where the testcase process is instantiated in the testbench top (tb_example1). The old example where the testcase process is located in a VHDL component of its own, is now called example_tb2.</td>
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<tr>
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<td>Updates for beta0002: added description of toAscending(), toDescending(), hxstr(), functions and procedures in txt_util.vhd.</td>
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<td>Updates for beta0003: added to VHDL versions and simulators to feature list. Added check() for boolean and for time with tolerance. In section User Configuration, added info on pltbutils_files.lst.</td>
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<td>26/01/2016</td>
<td>Per Larsson</td>
<td>Updates for pltbutils v1.0: minor corrections.</td>
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1 Introduction

Overview

PlTbUtils makes it easy to create automatic, self-checking simulation testbenches, and to locate bugs during a simulation. It is a collection of functions, procedures and testbench components that simplifies creation of stimuli and checking results of a device under test.

Features:

- Simulation status printed in transcript windows as well as in waveform window (error count, checks count, number and name of current test, etc).
- Check procedures which output meaningful information when a check fails.
- Clear SUCCESS/FAIL message at end of simulation.
- Easy to locate point in time of bugs, by studying increments of the error counter in the waveform window.
- User-defined information messages in the waveform window about what is currently going on.
- Transcript outputs prepared for parsing by scripts, e.g. in regression tests.
- Configurable status messages for use in continuous integration environments, e.g. TeamCity.
- Reduces amount of code in tests, which makes them faster to write and easier to read.
- Tests can easily be included or skipped in a test run.
- Supports VHDL-93 and later.
- Supports most popular VHDL simulators, including ModelSim and ISim.

It is intended that PlTbUtils will constantly expand by adding more and more functions, procedures and testbench components. Comments, feedback and suggestions are welcome to pela.opencores@gmail.com.

Project web page: http://opencores.org/project.pltbutils.
Subversion repository URL: http://opencores.org/ocsvn/pltbutils/pltbutils/trunk
Subversion export command:

svn export http://opencores.org/ocsvn/pltbutils/pltbutils/trunk pltbutils
Acknowledgements

PlTbUtils contains the file txt_util.vhd by Stefan Doll and James F. Frenzel.
Thanks to Stefan Eriksson for suggestions and feedback.

Language

PlTbUtils complies with VHDL-1993 and later, so it works with most VHDL simulators.
It is possible to configure the way a simulation stops, by taking advantage of the
VHDL-2008 keywords stop and finish. If your simulator supports stop and/or
finish, see Configuring Simulation Halt on page 25.
A quick look

During a simulation, the waveform window shows current test number, test name, user-defined info, accumulated number of checks and errors. When the error counter increments, a bug has been found in that point in time.
The transcript window clearly shows points in time where the simulation starts, ends, and where errors are detected. The simulation stops with a clear SUCCESS/FAIL message, specifically formatted for parsing by scripts.
--- START OF SIMULATION ---

testcase: tcl
0 ps

Test 1: Reset test (0 ps)
Done with Test 1: Reset test (1000 ps)

Test 2: Simple sum test (15000 ps)
Done with Test 2: Simple sum test (35000 ps)

Test 3: Simple carry in test (65000 ps)
Done with Test 3: Simple carry in test (65000 ps)

Test 4: Simple carry out test (55000 ps)
Done with Test 4: Simple carry out test (75000 ps)

--- END OF SIMULATION ---

Note: The results presented below are based on the PITbUtils’ check() procedure calls.

The design may contain some errors, for which there are no check() calls.

7334
6 Tests
0 Skipped tests
0 Checks
0 Errors

--- SUCCESS ---

(VSM ID)
The testcase code is compact and to the point, which results in less code to write, and makes the code easier to read, as in the following example.

```vhdl
-- NOTE: The purpose of the following code is to demonstrate some of the -- features in PlTbUtils, not to do a thorough verification.
p_tc1 : process
variable pltbv : pltbv_t := C_PLTBV_INIT;
begin
  startsim("tc1", "", pltbv, pltbs);
  rst <= '1';
  carry_in <= '0';
  x <= (others => '0');
  y <= (others => '0');
  starttest(1, "Reset test", pltbv, pltbs);
  waitclks(2, clk, pltbv, pltbs);
  check("Sum during reset", sum, 0, pltbv, pltbs);
  check("Carry out during reset", carry_out, '0', pltbv, pltbs);
  rst <= '0';
  endtest(pltbv, pltbs);
  starttest(2, "Simple sum test", pltbv, pltbs);
  carry_in <= '0';
  x <= std_logic_vector(to_unsigned(1, x'length));
  y <= std_logic_vector(to_unsigned(2, x'length));
  waitclks(2, clk, pltbv, pltbs);
  check("Sum", sum, 3, pltbv, pltbs);
  check("Carry out", carry_out, '0', pltbv, pltbs);
  endtest(pltbv, pltbs);
  starttest(3, "Simple carry in test", pltbv, pltbs);
  print(G_DISABLE_BUGS=0, pltbv, pltbs, "Bug here somewhere");
  carry_in <= '1';
  x <= std_logic_vector(to_unsigned(1, x'length));
  y <= std_logic_vector(to_unsigned(2, x'length));
  waitclks(2, clk, pltbv, pltbs);
  check("Sum", sum, 4, pltbv, pltbs);
  check("Carry out", carry_out, '0', pltbv, pltbs);
  print(G_DISABLE_BUGS=0, pltbv, pltbs, "");
  endtest(pltbv, pltbs);
  starttest(4, "Simple carry out test", pltbv, pltbs);
  carry_in <= '0';
  x <= std_logic_vector(to_unsigned(2**G_WIDTH-1, x'length));
  y <= std_logic_vector(to_unsigned(1, x'length));
  waitclks(2, clk, pltbv, pltbs);
  check("Sum", sum, 0, pltbv, pltbs);
  check("Carry out", carry_out, '1', pltbv, pltbs);
  endtest(pltbv, pltbs);
  endsim(pltbv, pltbs, true);
end process p_tc1;
```
2

Tutorial

Basics

We will demonstrate how to use PITbUtils by showing an example. In this example, we have a DUT (Device Under Test / Design Under Test) with the following entity.

```vhdl
entity dut_example is
  generic (
    G_WIDTH         : integer := 8;
    G_DISABLE_BUGS  : integer range 0 to 1 := 1
  );
  port (
    clk_i           : in  std_logic;
    rst_i           : in  std_logic;
    carry_i         : in  std_logic;
    x_i             : in  std_logic_vector(G_WIDTH-1 downto 0);
    y_i             : in  std_logic_vector(G_WIDTH-1 downto 0);
    sum_o           : out std_logic_vector(G_WIDTH-1 downto 0);
    carry_o         : out std_logic
  );
end entity dut_example;
```

As you can see, it has a clock- and a reset input port (clk_i and rst_i), three other input ports (x_i, y_i, and carry_i), and two output ports (sum_o and carry_o). There is also a generic, G_WIDTH, which sets the number of bits in x_i, y_i and sum_o. The second generic, G_DISABLE_BUGS, is very unusual in real designs, but it is useful in this example. We will reveal the purpose of this strange generic later, although some may already be able to guess what it is for.

To verify this DUT, we want the testbench to apply different stimuli to the input ports, and check the response of the output ports. The following code is an example of such a testbench. We will first show all of the code, and then explain parts of it.
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
use work.txt_util.all;
use work.pltbutils_func_pkg.all;
use work.pltbutils_comp_pkg.all;

data type;

entity tb_example is
  generic(
    G_WIDTH             : integer := 8;
    G_CLK_PERIOD        : time := 10 ns;
    G_DISABLE_BUGS      : integer range 0 to 1 := 0
  );
end entity tb_example;

architecture bhv of tb_example is

  -- Simulation status and control signals
  -- for accessing .stop_sim and for viewing in waveform window
  signal pltbs          : pltbs_t := C_PLTBS_INIT;

  -- DUT stimuli and response signals
  signal clk            : std_logic;
  signal rst            : std_logic;
  signal carry_in       : std_logic;
  signal x              : std_logic_vector(G_WIDTH-1 downto 0);
  signal y              : std_logic_vector(G_WIDTH-1 downto 0);
  signal sum            : std_logic_vector(G_WIDTH-1 downto 0);
  signal carry_out      : std_logic;

begin

  dut0 : entity work.dut_example
    generic map (    
      G_WIDTH           => G_WIDTH,
      G_DISABLE_BUGS    => G_DISABLE_BUGS
    )
    port map (    
      clk_i           => clk,
      rst_i           => rst,
      carry_i          => carry_in,
      x_i              => x,
      y_i              => y,
      sum_o            => sum,
      carry_o          => carry_out
    );

  clkgen0 : pltbutils_clkgen
    generic map (    
      G_PERIOD          => G_CLK_PERIOD
    )
    port map (    
      clk_o           => clk,
      stop_sim_i      => pltbs.stop_sim
    );
-- Testcase process
-- NOTE: The purpose of the following code is to demonstrate some of the
-- features of PlTbUtils, not to do a thorough verification.
p_tc1 : process
variable pltbv : pltbv_t := C_PLTBV_INIT;
begin
startsim("tc1", "", pltbv, pltbs);
  rst         <= '1';
  carry_in    <= '0';
  x           <= (others => '0');
  y           <= (others => '0');
  starttest(1, "Reset test", pltbv, pltbs);
  waitclks(2, clk, pltbv, pltbs);
  check("Sum during reset",       sum,         0, pltbv, pltbs);
  check("Carry out during reset", carry_out, '0', pltbv, pltbs);
  rst         <= '0';
  endtest(pltbv, pltbs);
  starttest(2, "Simple sum test", pltbv, pltbs);
  carry_in <= '0';
  x          <= std_logic_vector(to_unsigned(1, x'length));
  y          <= std_logic_vector(to_unsigned(2, x'length));
  waitclks(2, clk, pltbv, pltbs);
  check("Sum",       sum,         3, pltbv, pltbs);
  check("Carry out", carry_out, '0', pltbv, pltbs);
  endtest(pltbv, pltbs);
  starttest(3, "Simple carry in test", pltbv, pltbs);
  print(G_DISABLE_BUGS=0, pltbv, pltbs, "Bug here somewhere");
  carry_in <= '1';
  x          <= std_logic_vector(to_unsigned(1, x'length));
  y          <= std_logic_vector(to_unsigned(2, x'length));
  waitclks(2, clk, pltbv, pltbs);
  check("Carry out", carry_out, '0', pltbv, pltbs);
  print(G_DISABLE_BUGS=0, pltbv, pltbs, "");
  endtest(pltbv, pltbs);
  starttest(4, "Simple carry out test", pltbv, pltbs);
  carry_in <= '0';
  x          <= std_logic_vector(to_unsigned(2**G_WIDTH-1, x'length));
  y          <= std_logic_vector(to_unsigned(1, x'length));
  waitclks(2, clk, pltbv, pltbs);
  check("Sum",       sum,         0, pltbv, pltbs);
  check("Carry out", carry_out, '1', pltbv, pltbs);
  endtest(pltbv, pltbs);
endtest(pltbv, pltbs, true);
end process p_tc1;
end architecture bhv;
As the testbench example shows, the following packages are needed (in addition to the usual std_logic_1164, etc):

use work.txt_util.all;
use work.pltbutils_func_pkg.all;
use work.pltbutils_comp_pkg.all;

txt_util contains functions and procedures for handling strings.

pltbutils_func_pkg contains type definitions, functions and procedures for controlling stimuli and checking response.

pltbutils_comp_pkg contains component declarations for testbench components.

PlTbUtils uses a variable called pltbv, and a signal called pltbs, for controlling the simulation and keeping track of status. The pltbs signal is useful for viewing in the simulator’s waveform window. pltbs is a record containing a number of members which show various information. Expand pltbs in the simulator’s waveform window to expose the members. To make it prettier, you can make use of ModelSim’s Combine Signals feature. Each member of the pltbs record can be set to be its own Combined Signal, see the waveform images in this document. Other simulators usually have similar features.

The DUT is instansiated in the testbench, as well as a clock generator component from PlTbUtils.

There is also a testcase process, which feeds the DUT with stimuli, and checks the results.

The testcase process starts with calling the procedure startsim(). This procedure initializes pltbv and pltbs, and outputs a message to the transcript and to the waveform window to inform that the simulation now starts. The first argument to startsim is the name of the testcase. The second argument is an empty vector in this example. The purpose of this argument will be explained later.

The last arguments of startsim(), and to many other procedures in PlTbUtils, are pltbv and pltbs.

After initiating stimuli to the DUT, we call the procedure starttest() with the number and name for the first test. starttest() prints the test number and test name to the transcript and to the waveform window, and updates pltbv and pltbs.

Then we need to wait until the DUT has reacted to the stimuli. We do this by calling the procedure waitclks(), which waits a specified number of cycles of the specified clock.

After this, we start checking the results, by examining the outputs from the DUT. To do this, we use the check() procedure. The first argument is a text string that specifies what we check, the second argument is the signal or variable that we want to examine, and the third is the expected value of the signal or variable. If the examined signal holds the expected value, nothing is printed. But if the value is incorrect, the string in the first argument is printed, together with the actual and expected values of the signal. The number and name of the test (as specified with starttest() ) is also printed. PlTbUtils’ check counter is incremented for every check() procedure call, and the error counter is incremented in case of error.
After the test, we call endtest().

We make a number of different tests by calling starttest(), setting stimuli, waiting for the DUT to react with waitclks() or some other means, and checking the outputs with the check() procedure, and calling endtest().

Finally, we call the endsim() procedure, which prints an end-of-simulation message to the transcript, and presents the results, including a SUCCESS or FAIL message.

The start-of-simulation message, end-of-simulation message, and SUCCESS/FAIL messages have a unique formatting with three dashes or asterisks before and after the message. This make them easy to search for by scripts, to simplify collection of simulation status of regression tests with a lot of different simulations.

Try it out in your simulator! The pltbutils files that need to be compiled are located in src/vhdl/, and they are listed in compile order in pltbutils_files.lst. The example DUT file is located in examples/vhdl/rtl_example/, and the example testbench files are located in examples/vhdl/example1/. The files are listed in compile order in example_dut.lst and tb_example1_files.lst.

If you are a ModelSim user, there are .do files available in sim/modelsim_tb_example1/run/. To use them, start Start ModelSim, and in the ModelSim Gui select the menu item File->Change directory... . Navigate to the PlTbUtils directory sim/modelsim_tb_example1/run/ and click Ok. Then, in the transcript window, type do run.do
The simulation will start, and the transcript from the simulation looks as follows.

```
# Loading std_logic
# Loading std.textio
# Loading ieee.numeric_std
# Loading work.testutil
# Loading work.pitbutils_user_cfg
# Loading work.pitbutils_func
# Loading work.tb_example
# Loading work.out_example
# Loading work.pitbutils_clkgen

--- START OF SIMULATION ---
BarName: Col
0 ps
Test 1: Reset test (0 ps)
Done with test 1: Reset test (0 ps)
Test 2: Simple sum test (5000 ps)
Done with test 2: Simple sum test (5000 ps)
Test 3: Simple carry in test (15000 ps)
** Error: Check 3: Sum: Actual-67570 Expected-67564 in test 3 Simple carry in test
Times: 35 ns Iteration: 1 Instance: /tb_example
Done with test 3: Simple carry in test (15000 ps)
Test 4: Simple carry out test (5000 ps)
Done with test 4: Simple carry out test (5000 ps)
--- END OF SIMULATION ---
Note: the results presented below are based on the PITbUtil's check() procedure calls.
The design may contain more errors, for which there are no check() calls.
75 ps
4 Tests
0 Skipped tests
0 Checks
1 Error
*** FAIL ***

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The transcript says that one error has been found at 55 ns, in test 3; Simple carry in test.
The waveform window looks like this.

Here we can see the error detected at the point in time where the error counter increments from 0 to 1. Again, we can that the error is found in test 3, the Simple carry in test.

Have a look at the DUT code in examples/vhdl/rtl_example/dut_example.vhd. It looks as follows.
x <= resize(unsigned(x_i), G_WIDTH+1);
y <= resize(unsigned(y_i), G_WIDTH+1);
c <= resize(unsigned(std_logic_vector('0' & carry_i)), G_WIDTH+1);

p_sum : process(clk_i)
begin
  if rising_edge(clk_i) then
    if rst_i = '1' then
      sum <= (others => '0');
    else
      if G_DISABLE_BUGS = 1 then
        sum <= x + y + c;
      else
        sum <= x + y;
      end if;
    end if;
  end if;
end process;

The code really looks suspicious. If the generic G_DISABLE_BUGS is not one, the carry input is not added to the sum. But we need the carry input to be added to the sum!

A simple way to disable this bug, is to set the generic G_DISABLE_BUGS to one. In this case, this can be done very easily, without any modifying of the code.

In the ModelSim transcript window, type

do run_bugfixed.do

This will run the test again, but now with the generic G_DISABLE_BUGS set to 1.

The transcript and waveform windows will now look like the following images.
```c
# START OF SIMULATION
\nTestcase: tcl
\n0 ps
Test 1: Reset test (0 ps)
  Done with test 1: Reset test (10000 ps)
Test 2: Simple sum test (15000 ps)
  Done with test 2: Simple sum test (35000 ps)
Test 3: Simple carry in test (35000 ps)
  Done with test 3: Simple carry in test (55000 ps)
Test 4: Simple carry out test (55000 ps)
  Done with test 4: Simple carry out test (75000 ps)

--- END OF SIMULATION ---

Note: the results presented below are based on the PITbUtil's check() procedure calls.

The design may contain more errors, for which there are no check() calls.

    75 no
    4 tests
    3 skipped tests
    8 checks
    18 errors

*** SUCCESS ***
```
This tutorial has shown some of the available procedures and testbench components in PITbUtils. For a complete list, see the reference section.

When you want to make your own testbenches with PITbUtils, have a look at the template files in templates/vhdl/template1/.
Different kinds of check()

There are a number of overloaded check() procedures for different VHDL types, e.g. std_logic, std_logic_vector, unsigned, signed, integer, boolean, time, etc. See the Reference section for a complete list. The check() procedures checks equality, i.e. that a signal or variable has an expected value. They have the form

\[
\text{check(rpt, actual, expected, pltbv, pltbs)}
\]

where \( \text{rpt} \) is the string message with info on what is being checked, \( \text{actual} \) is the signal or variable to check, and \( \text{expected} \) is the expected value. If the check fails, \( \text{rpt} \) is printed together with \( \text{actual} \) and \( \text{expected} \) valued. There is no need to include the expected value in the \( \text{rpt} \) string, because it is printed anyway.

There is no support for comparisons other than equality, such as greater than, or not equal. But there is one check procedure that can be used for composing your own expression:

\[
\text{check(rpt, expr, pltbv, pltbs)}
\]

Replace \( \text{expr} \) with your own expression.

\[
\text{check("Counter after data burst", cnt_o > 10, pltbv, pltbs);}
\]

Note that if the test fails, the actual and expected values will not be printed (because this check() procedure does not get any information on actual and expected value. You may include that information in the \( \text{rpt} \) message if you want to.

\[
\text{check("Counter after data burst": " & str(cnt_o) & " expected > 10", cnt_o > 10, pltbv, pltbs);}
\]

You can create specialized check procedures in a package file of your own. Your package file should begin with

\[
\text{use work.txt_util.all;}
\]
\[
\text{use work.pltbutils_func_pkg.all;}
\]

and your own check procedure should call

\[
\text{check(rpt, expr, actual, expected, mask, pltbv, pltbs)}
\]

where \( \text{actual} \), \( \text{expected} \) and \( \text{mask} \) are strings.

Example:

\[
-- \text{check greater than, unsigned}
\]
\[
\text{procedure check_gt(}
\]
\[
\begin{align*}
\text{constant rpt} & : \text{ in string;} \\
\text{constant actual} & : \text{ in unsigned;} \\
\text{constant expected} & : \text{ in unsigned;} \\
\text{variable pltbv} & : \text{ inout pltbv_t;} \\
\text{signal pltbs} & : \text{ out pltbs_t }
\end{align*}
\]
\[
\text{) is}
\]
\[
\begin{align*}
\text{begin} \\
\text{check(rpt, actual > expected, str(actual), ">" & str(expected), ",", pltbv, pltbs);}
\text{end procedure check_gt;}
\end{align*}
\]
Testbench with multiple testcases

In some cases, it is more convenient to not include the testcase process in the testbench top. Instead, we can put the testcase process in its own VHDL component. Then we can have alternative architectures for this component, with different testcase processes.

This is practical for large testbenches with a lot of testbench components and other code, with a requirement for multiple testcases. Then we don’t have to write a new testbench for each testcase.

The following is an example of such a testbench.
library ieee;
use ieee.std_logic_1164.all;
use work.pltbutils_func_pkg.all;
use work.pltbutils_comp_pkg.all;

entity tb_example2 is
  generic (
    G_WIDTH             : integer := 8;
    G_CLK_PERIOD        : time := 10 ns;
    G_DISABLE_BUGS      : integer range 0 to 1 := 0
  );
end entity tb_example2;

architecture bhv of tb_example2 is

  -- Simulation status- and control signals
  -- for accessing .stop_sim and for viewing in waveform window
  signal pltbs          : pltbs_t := C_PLTBS_INIT;

  -- DUT stimuli and response signals
  signal clk            : std_logic;
  signal rst            : std_logic;
  signal carry_in       : std_logic;
  signal x              : std_logic_vector (G_WIDTH - 1 downto 0);
  signal y              : std_logic_vector (G_WIDTH - 1 downto 0);
  signal sum            : std_logic_vector (G_WIDTH - 1 downto 0);
  signal carry_out      : std_logic;

begin

dut0 : entity work.dut_example
generic map (
  G_WIDTH           => G_WIDTH,
  G_DISABLE_BUGS    => G_DISABLE_BUGS
)
port map (
  clk_i             => clk,
  rst_i             => rst,
  carry_i           => carry_in,
  x_i               => x,
  y_i               => y,
  sum_o             => sum,
  carry_o           => carry_out
);

clkgen0 : pltbutils_clkgen
generic map(
  G_PERIOD          => G_CLK_PERIOD
)
port map(
  clk_o             => clk,
  stop_sim_i        => pltbs.stop_sim
);

tc0 : entity work.tc_example2
generic map (
  G_WIDTH           => G_WIDTH,
  G_DISABLE_BUGS    => G_DISABLE_BUGS
)
port map(
  pltbs             => pltbs,
  clk               => clk,
  rst               => rst,
  carry_in          => carry_in,
  x                 => x,
  y                 => y,
  sum               => sum,
  c_CLK_PERIOD      => G_CLK_PERIOD
);
Instead of a testcase process, we instantiate a testcase component (tc_example2). This testcase component has an entity defined in one file, and the architecture defined in another file. This makes it possible to have several different testcases for the same testbench. Just compile the testcase architecture that you want to use for a specific simulation run.

The entity declaration for the testcase looks as follows.

```vhlp
library ieee;
use ieee.std_logic_1164.all;
use work.pltbutils_func_pkg.all;

entity tc_example is
  generic (
    G_WIDTH         : integer := 8;
    G_DISABLE_BUGS  : integer range 0 to 1 := 0
  );
  port (
    pltbs           : out pltbs_t;
    clk             : in  std_logic;
    rst             : out std_logic;
    carry_in        : out std_logic;
    x               : out std_logic_vector(G_WIDTH-1 downto 0);
    y               : out std_logic_vector(G_WIDTH-1 downto 0);
    sum             : in  std_logic_vector(G_WIDTH-1 downto 0);
    carry_out       : in  std_logic
  );
end entity tc_example;
```

The ports of the testcase components are the same as for the DUT, but the mode (direction) of the ports are the opposite, so the testcase component can drive the inputs of the DUT, and detect the values of the output of the DUT. The only exception to this rule is the clock, which is an input, just as for the DUT.

There is also an output port for pltbs, because pltbs is driven from the tc architecture.

The entity is stored in its’ own file.

The architecture contains the testcase process. There can be several different architecture files. The architecture looks as follows.
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
use work.txt_util.all;
use work.pltbutils.func_pkg.all;

-- NOTE: The purpose of the following code is to demonstrate some of the
-- features in PlTbUtils, not to do a thorough verification.
architecture tc1 of tc_example2 is
begin
  p_tc1 : process
  variable pltbv : pltbv_t := C_PLTBV_INIT;
  begin
    startsim("tc1", "", pltbv, pltbs);
    rst <= '1';
    carry_in <= '0';
    x    <= (others => '0');
    y    <= (others => '0');
    starttest(1, "Reset test", pltbv, pltbs);
    waitclks(2, clk, pltbv, pltbs);
    check("Sum during reset", sum, 0, pltbv, pltbs);
    rst <= '0';
    endtest(pltbv, pltbs);
    startsim(2, "Simple sum test", pltbv, pltbs);
    carry_in <= '0';
    x    <= std_logic_vector(to_unsigned(1, x'length));
    y    <= std_logic_vector(to_unsigned(2, x'length));
    waitclks(2, clk, pltbv, pltbs);
    check("Sum", sum, 3, pltbv, pltbs);
    check("Carry out during reset", carry_out, '0', pltbv, pltbs);
    waitsim(2, clk, pltbv, pltbs);
    starttest(3, "Simple carry in test", pltbv, pltbs);
    print(G_DISABLE_BUGS=0, pltbv, pltbs, "Bug here somewhere");
    carry_in <= '1';
    x    <= std_logic_vector(to_unsigned(1, x'length));
    y    <= std_logic_vector(to_unsigned(2, x'length));
    waitclks(2, clk, pltbv, pltbs);
    check("Sum", sum, 4, pltbv, pltbs);
    check("Carry out", carry_out, '0', pltbv, pltbs);
    print(G_DISABLE_BUGS=0, pltbv, pltbs, "");
    endtest(pltbv, pltbs);
    startsim(4, "Simple carry out test", pltbv, pltbs);
    carry_in <= '0';
    x    <= std_logic_vector(to_unsigned(2**G_WIDTH-1, x'length));
    y    <= std_logic_vector(to_unsigned(1, x'length));
    waitclks(2, clk, pltbv, pltbs);
    check("Sum", sum, 0, pltbv, pltbs);
    check("Carry out", carry_out, '1', pltbv, pltbs);
    endtest(pltbv, pltbs);
    endsim(pltbv, pltbs, true);
  end process p_tc1;
end architecture tc1;

Try this too in your simulator. The example testbench files are located in
examples/vhdl/example2/. The files are listed in compile order in tb_example2_files.lst. If
you are a ModelSim user, there are .do files available in
sim/modelsim_tb_example2/run/. To use them, start Start ModelSim, and in the ModelSim Gui select the menu item...
File->Change directory... . Navigate to the PITbUtils directory sim/modelsim_tb_example2/run/ and click Ok. Then, in the transcript window, type
do run_tcl.do

Also try
do run_tcl_bugfixed.do

Template files for this type of testbench is available in templates/vhdl/template2/ .
Skipping tests

PlTbUtils lets you skip tests, if you want to. This is useful while debugging a failure in a test. You can save simulation time by skipping the tests before and after the failing test. It is also useful while developing a test to skip the tests before.

To skip a test, add generic G_SKIPTESTS to the testbench of type std_logic_vector.

```vhdl
entity tb_example1_skip is
genrics (
    G_WIDTH             : integer := 8;
    G_CLK_PERIOD        : time := 10 ns;
    G_DISABLE_BUGS      : integer range 0 to 1 := 0;
    G_SKIPTESTS         : std_logic_vector := ('0', -- Dummy
                                              '0', -- Test 1
                                              '0' -- Test 2
                                              -- ... etc
    )
end entity tb_example1_skip;
```

If a bit in the vector is ‘1’, the corresponding test is skipped. Bits are counted from 0 and upwards. There is usually no test with number 0, so bit 0 is usually a dummy. The length of the vector does not have to match the number of tests. If the vector is shorter, the remaining tests will not be skipped. If the vector is longer, the excessive bits will be ignored.

Feed this generic as the second argument of startsim().

```vhdl
startsim("tc1", G_SKIPTESTS, pltbv, pltbs);
```

For each test, add an if-clause that calls is_test_active(pltbv) and executes or skips the test.

```vhdl
starttest(1, "Reset test", pltbv, pltbs);
if is_test_active(pltbv) then
    waitclks(2, clk, pltbv, pltbs);
    check("Sum during reset",       sum,         0, pltbv, pltbs);
    check("Carry out during reset", carry_out, '0', pltbv, pltbs);
    rst         <= '0';
end if; -- is_test_active()
endtest(pltbv, pltbs);
```

If is_test_active(pltbv) returns true, the test will be executed as usual. If it returns false, PlTbUtils outputs a message like the following, and skips the test.

**Skipping Test 1: Reset test**

Note that if you forget the if-clause, the “skipping test message” will be displayed, but the test will be executed anyway. If a check() procedure is called within a skipped test (if there is no if-clause), an error message will be displayed, and the error counter will be incremented.

The skip functionality is included in the templates in templates/vhdl/template1/ and templates/vhdl/template2/.
It is of course also possible to define the generic in the following form:

```vhdl
G_SKIPTESTS : std_logic_vector := "001";
```

This is more compact as it uses only a single line, but it is not possible to add individual comments for each test.
User Configuration

It is possible to configure some aspects of PlTbUtils’s behaviour, by modifying the package file pltbutils_user_cfg.pkg.

It is recommended NOT to modify the file directly. Instead, copy it to another directory and modify the copy. Make the simulator read the modified copy instead of the original. This makes it easier to update pltbutils to a later version without destroying the modifications. After updating, check if anything has changed in the file, and change your modified copy accordingly.

If your simulation environment (scripts, etc) uses the file pltbutils_files.lst, then copy it too, to the other directory. Modify the contents of the file, by modifying the relative paths to point to the files from the new location.

Configuring Simulation Halt

When calling endsim(), the signal stop_sim is set to ‘1’. When set, all clock generators etc in the testbench and the DUT should stop, so there will be no further events in the simulation. The simulator will detect that nothing more will happen, and stops the simulation.

In some cases, it is not possible to stop clock generators, PLL models etc. In that case, endsim() can force a simulation halt, by setting the force argument to true.

The declaration of endsim() is

```
procedure endsim(
  signal pltbutils_sc : out pltbutils_sc_t;
  constant show_success_fail : in  boolean := false;
  constant force              : in  boolean := false
);
```

so to force a simulation halt, call endsim with

```
endsim(pltbutils_sc, true, true);
```

This stops the simulation using an assert-failure. This works in all versions of VHDL, but it is an ugly way of doing it, since it outputs a failure message for something which isn’t a failure.

You can change the way the simulation stops when the force flag is set in your copy of pltbutils_user_cfg.vhd.

Change the constant `C_PLTBUTILS_USE_CUSTOM_STOPSIM` to true, and modify the behavior of the procedure `custom_stopsim()`. In VHDL-2008 the new keywords `stop` and `finish` was introduced. Try one of them, if your simulator supports them.
Configuring Messages for Integration Environments

It is possible adapt the status messages to suit various continous integration environments, e.g. TeamCity, by specifying what the messages should look like.

You can create your own messages printed when starting and stopping a simulation, starting and stopping a test, for checking, etc.

In your copy of pltbutils_user_cfg_pkg.vhd, set one or more of the message constants to true, and modify the associated procedure.

The constants are

- `C_PLTBUTILS_USE_CUSTOM_STARTSIM_MSG`
- `C_PLTBUTILS_USE_CUSTOM_ENDSIM_MSG`
- `C_PLTBUTILS_USE_CUSTOM_STARTTEST_MSG`
- `C_PLTBUTILS_USE_CUSTOM_ENDTEST_MSG`
- `C_PLTBUTILS_USE_CUSTOM_CHECK_MSG`
- `C_PLTBUTILS_USE_CUSTOM_ERROR_MSG`

The corresponding procedures already contain examples for TeamCity. Modify if you use another environment.

You can disable the standard messages by setting the standard constants to false (e.g., `C_PLTBUTILS_USE_STD_STARTSIM_MSG` etc).

Differences between simulators

Reference

PITbUtils files

The PITbUtils files are located in src/vhdl/.
The files needed to be compiled are listed in compile order in pltbutils_files.lst.

See example testbenches using PITbUtils in examples/vhdl/.
This code can be simulated from sim/modelsim_tb_example1/run/ and sim/modelsim_tb_example2/run/.

Template code is available in templates/vhdl/.
Functions and procedures

**startsim**

```vhdl
procedure startsim(
    constant testcase_name      : in    string;
    constant skiptests          : in    std_logic_vector;
    variable pltbv              : inout pltbv_t;
    signal   pltbs              : out   pltbs_t
)  

Displays a message at start of simulation message, and initializes PITbUtils' status and control variable and -signal. Call startsim() only once.

Arguments:

- **testcase_name**
  Name of the test case, e.g. "tc1".

- **skiptests**
  std_logic_vector for marking tests that should be skipped. The leftmost bit has position 0, and position numbers increment to the right. A '1' indicates that the test with the same number as the position should be skipped. Note that there is usually no test which has number 0, so bit zero in the vector is usually ignored. This argument is normally fed by a generic. If no tests should be skipped, a zero-length vector is allowed, ("").

- **pltbv, pltbs**
  PITbUtils' status- and control variable and -signal.

The start-of-simulation message is not only intended to be informative for humans. It is also intended to be searched for by scripts, e.g. for collecting results from a large number of regression tests.

Examples:

```vhdl
startsim("tc1", "", pltbv, pltbs);
startsim("tc2", G_SKIPTESTS, pltbv, pltbs); -- G_SKIPTESTS is a generic
```
endsim

procedure endsim(
    variable pltbv              : inout pltbv_t;
    signal   pltbs              : out   pltbs_t;
    constant show_success_fail : in  boolean := false;
    constant force              : in  boolean := false
)

Displays a message at end of simulation message, presents the simulation results, and stops the simulation. Call endsim() it only once.

Arguments:

pltbv, pltbs      PITbUtils' status- and control variable and -signal.
show_success_fail If true, endsim() shows "*** SUCCESS ***", "*** FAIL ***", or "*** NO CHECKS ***". Optional, default is false.
force             If true, forces the simulation to stop using an assert failure statement. Use this option only if the normal way of stopping the simulation doesn't work (see below). Optional, default is false.

The testbench should be designed so that all clocks stop when endsim() sets the signal stop_sim to '1'. This should stop the simulator.

In some cases, that doesn't work, then set the force argument to true, which causes a false assert failure, which should stop the simulator.

The end-of-simulation messages and success/fail messages are not only intended to be informative for humans. They are also intended to be searched for by scripts, e.g. for collecting results from a large number of regression tests.

Examples:

endsim(pltbv, pltbs);
endsim(pltbv, pltbs, true);
endsim(pltbv, pltbs, true, true);
**starttest**

procedure starttest(  
  constant num : in integer := -1;  
  constant name: in string;  
  variable pltbv : inout pltbv_t;  
  signal pltbs  : out pltbs_t  
)

Sets a number (optional) and a name for a test. The number and name will be printed to the screen, and displayed in the simulator's waveform window.

The test number and name is also included if there errors reported by the check() procedure calls.

Arguments:

num Test number. Optional, default is to increment the current test number.

name Test name.

pltbv, pltbs PlTbUtils' status- and control variable and -signal.

If the test number is omitted, a new test number is automatically computed by incrementing the current test number. Manually setting the test number may make it easier to find the test code in the testbench code, though.

Examples:

starttest("Reset test", pltbv, pltbs);  
starttest(1, "Reset test", pltbv, pltbs);
function is_test_active(
    constant pltbv              : in    pltbv_t
) return boolean

Returns true if a test is active (not skipped), otherwise false.
Arguments:
pltbv           PITbUtils' status- and control variable.

Example:
starttest(3, "Example test", pltbv, pltbs);
if is_test_active(pltbv) then
    ... test code ... 
end if;
endtest(pltbv, pltbs);
endtest

procedure endtest(
    variable pltbv : inout pltbv_t;
    signal pltbs : out pltbs_t
)

Prints an end-of-test message to the screen.

Arguments:
pltbv, pltbs    PITbUtils' status- and control variable and -signal.

Example:
endtest(pltbv, pltbs);
**print printv print2**

*Defined in txt_util.vhd:*

```vhdl
procedure print(
    constant txt                 : in    string
)

procedure print(
    constant active             : in    boolean;
    constant txt                 : in    string
)
```

*Defined in pltbutils_func_pkg.vhd:*

```vhdl
procedure print(
    signal   s                  : out   string;
    constant txt                 : in    string
)

procedure print(
    constant active             : in    boolean;
    signal   s                  : out   string;
    constant txt                 : in    string
)

procedure print(
    variable pltbv              : inout pltbv_t;
    signal   pltbs              : out   pltbs_t;
    constant txt                 : in    string
)

procedure print(
    constant active             : in    boolean;
    variable pltbv              : inout pltbv_t;
    signal   pltbs              : out   pltbs_t;
    constant txt                 : in    string
)```
procedure printv(
    variable s : out string;
    constant txt : in string
)

procedure printv(
    constant active : in boolean;
    variable s : out string;
    constant txt : in string
)

procedure print2(
    signal s : out string;
    constant txt : in string
)

procedure print2(
    constant active : in boolean;
    signal s : out string;
    constant txt : in string
)

procedure print2(
    variable pltbv : inout pltbv_t;
    signal pltbs : out pltbs_t;
    constant txt : in string
)

procedure print2(
    constant active : in boolean;
    variable pltbv : inout pltbv_t;
    signal pltbs : out pltbs_t;
    constant txt : in string
)
print() without a signal as argument prints text messages to the transcript window.
print() with a signal as argument prints text messages to that signal for viewing in the
simulator's waveform window.
printv() does the same thing, but to a variable instead.
print2() prints both to a signal and to the transcript window.

The type of the output can be string or pltbv+pltbs.

Arguments:
s Signal or variable of type string to be printed to.
txt The text.
active The text is only printed if active is true. Useful for debug switches, etc.
pltbv, pltbs PITbUtils' status- and control variable and -signal. The text will be
printed to “info” in the waveform window.

If the string txt is longer than the signal s, the text will be truncated. If txt is shorter, s will
be padded with spaces.

Examples:

print("Hello, world"); -- Prints to transcript window
print(msg, "Hello, world"); -- Prints to signal msg
print(G_DEBUG, msg, "Hello, world"); -- Prints to signal msg if
  -- generic G_DEBUG is true
printv(v_msg, "Hello, world"); -- Prints to variable msg
print(pltbv, pltbs, "Hello, world"); -- Prints to “info” in waveform window
print2(msg, "Hello, world"); -- Prints to signal and transcript window
print(pltbv, pltbs, "Hello, world"); -- Prints to “info” in waveform and
  -- transcript windows
**waitclks**

procedure waitclks(
    constant n                  : in    natural;
    signal   clk                : in    std_logic;
    variable pltbv              : inout pltbv_t;
    signal   pltbs              : out   pltbs_t;
    constant falling            : in    boolean := false;
    constant timeout            : in    time    := C_PLTBUTILS_TIMEOUT
)

Waits specified amount of clock cycles of the specified clock. Or, to be more precise, a specified number of specified clock edges of the specified clock.

**Arguments:**

- **n** \(\quad\) Number of rising or falling clock edges to wait.
- **clk** \(\quad\) The clock to wait for.
- **pltbv, pltbs** \(\quad\) PITbUtils' status- and control variable and -signal.
- **falling** \(\quad\) If true, waits for falling edges, otherwise rising edges. Optional, default is false.
- **timeout** \(\quad\) Timeout time, in case the clock is not working. Optional, default is C_PLTBUTILS_TIMEOUT.

**Examples:**

```vhd
waitclks(5, sys_clk, pltbv, pltbs);
waitclks(5, sys_clk, pltbv, pltbs, true);
waitclks(5, sys_clk, pltbv, pltbs, true, 1 ms);
```
waitsig

procedure waitsig(
  signal   s                  : in
                          integer|std_logic|std_logic_vector|unsigned|signed;
constant value              : in
                          integer|std_logic|std_logic_vector|unsigned|signed;
signal   clk                : in    std_logic;
variable pltbv              : inout pltbv_t;
signal   pltbs              : out   pltbs_t;
constant falling            : in    boolean := false;
constant timeout            : in    time    := C_PLTBUTILS_TIMEOUT)

Waits until a signal has reached a specified value after specified clock edge.

Arguments:

s            The signal to test.
Supported types: integer, std_logic, std_logic_vector, unsigned, signed.
value        Value to wait for.
Same type as data or integer.
clk          The clock.
pltbv, pltbs PlTbUtils' status- and control variable and -signal.
falling      If true, waits for falling edges, otherwise rising edges.
Optional, default is false.
timeout      Timeout time, in case the clock is not working.
Optional, default is C_PLTBUTILS_TIMEOUT.

Examples:
waitsig(wr_en, '1', sys_clk, pltbv, pltbs);
waitsig(rd_en, '1', sys_clk, pltbv, pltbs, true);
waitclks(full, '1', sys_clk, pltbv, pltbs, true, 1 ms);
check

procedure check(
    constant rpt              : in    string;
    constant data             : in    std_logic_vector;
    constant expected         : in    std_logic_vector;
    constant mask             : in    std_logic_vector;
    variable pltbv            : inout pltbv_t;
    signal   pltbs            : out   pltbs_t
)
Checks that the value of a signal or variable is equal to expected. If not equal, displays an error message and increments the error counter.

Arguments:

rpt Report message to be displayed in case of mismatch. It is recommended that the message is unique and that it contains the name of the signal or variable being checked. The message should NOT contain the expected value, because check() prints that automatically.

data The signal or variable to be checked. Supported types: integer, std_logic, std_logic_vector, unsigned, signed.

expected Expected value. Same type as data, or integer.

mask Bit mask and:ed to data and expected before comparison. Optional if data is std_logic_vector. Not allowed for other types.

tolerance Allowed tolerance. Checks that expected - tolerance ≤ actual ≤ expected + tolerance is true.

expr boolean expression for checking. This makes it possible to check any kind of expression, not just equality.

pltbv, pltbs PITbUtils' status- and control variable and -signal.

Examples:

check("dat_o after reset", dat_o, 0, pltbv, pltbs);
-- With mask:
check("Status field in reg_o after start", reg_o, x"01", x"03", pltbv, pltbs);
-- Boolean expression:
check("Counter after data burst", cnt_o > 10, pltbv, pltbs);
to_ascending

function to_ascending(
    constant s                  : std_logic_vector | unsigned | signed
) return std_logic_vector | unsigned | signed;

Converts a vector to ascending range ("to-range").
The argument s can have ascending or descending range.
E.g. an argument defined as a std_logic_vector(3 downto 1)
will be returned as a std_logic_vector(1 to 3).

Arguments:

s          Constant, signal or variable to convert

Return value: Converted value

Examples:
ascending_sig <= to_ascending(descending_sig);
ascending_var := to_ascending(descending_var);

to_descending

function to_descending(
    constant s                  : std_logic_vector | unsigned | signed
) return std_logic_vector | unsigned | signed;

Converts a vector to descending range ("downto-range").
The argument s can have ascending or descending range.
E.g. an argument defined as a std_logic_vector(1 to 3)
will be returned as a std_logic_vector(3 downto 1).

Arguments:

s          Constant, signal or variable to convert

Return value: Converted value

Examples:
descending_sig <= to_descending(ascending_sig);
descending_var := to_descending(ascending_var);
**hxstr**

function hxstr(
    constant s            : std_logic_vector | unsigned | signed;
    constant prefix       : string := "";
    constant postfix      : string := ""
) return string;

Converts a vector to a string in hexadecimal format. An optional prefix can be specified, e.g. "0x", as well as a suffix.

The input argument can have ascending range ("to-range") or descending range ("downto-range"). There is no vector length limitation.

**Arguments:**
- s Constant, signal or variable to convert

**Return value:** Converted value

**Examples:**

print("value=" & hxstr(s));
print("value=" & hxstr(s, "0x");
print("value=" & hxstr(s, "16#", "#"));
More functions and procedures in `txt_util.vhd`

-- converts std_logic into a character
function chr(sl: std_logic) return character;

-- converts std_logic into a string (1 to 1)
function str(sl: std_logic) return string;

-- converts std_logic_vector into a string (binary base)
function str(slv: std_logic_vector) return string;

-- converts boolean into a string
function str(b: boolean) return string;

-- converts an integer into a single character
-- (can also be used for hex conversion and other bases)
function chr(int: integer) return character;

-- converts integer into string using specified base
function str(int: integer; base: integer) return string;

-- converts integer to string, using base 10
function str(int: integer) return string;

-- convert std_logic_vector into a string in hex format
-- NOTE: Argument limited to 32 bits. Consider hxstr(), see p 41.
function hstr(slv: std_logic_vector) return string;

-- functions to manipulate strings
-----------------------------------

-- convert a character to upper case
function to_upper(c: character) return character;

-- convert a character to lower case
function to_lower(c: character) return character;

-- convert a string to upper case
function to_upper(s: string) return string;

-- convert a string to lower case
function to_lower(s: string) return string;

-- checks if whitespace (JFF)
function is_whitespace(c: character) return boolean;

-- remove leading whitespace (JFF)
function strip_whitespace(s: string) return string;

-- return first nonwhitespace substring (JFF)
function first_string(s: string) return string;
-- finds the first non-whitespace substring in a string and (JFF)
-- returns both the substring and the original with the substring
-- removed
procedure chomp(variable s: inout string; variable shead: out string);

-- functions to convert strings into other formats
------------------------------------------
-- converts a character into std_logic
function to_std_logic(c: character) return std_logic;

-- converts a hex character into std_logic_vector (JFF)
function chr_to_slv(c: character) return std_logic_vector;

-- converts a character into int (JFF)
function chr_to_int(c: character) return integer;

-- converts a binary string into std_logic_vector
function to_std_logic_vector(s: string) return std_logic_vector;

-- converts a hex string into std_logic_vector (JFF)
function hstr_to_slv(s: string) return std_logic_vector;

-- converts a decimal string into an integer (JFF)
function str_to_int(s: string) return integer;

-- file I/O
---------

-- read variable length string from input file
procedure str_read(file in_file: TEXT;
    res_string: out string);

-- print string to a file and start new line
procedure print(file out_file: TEXT;
    new_string: in string);

-- print character to a file and start new line
procedure print(file out_file: TEXT;
    char: in character);
Testbench components

**pltbutils_clkgen**

Creates a clock signal for use in a testbench. The clock stops when input port stop_sim goes `‘1’`. This makes the simulator stop (unless there are other infinite processes running in the simulation).

<table>
<thead>
<tr>
<th>Generic</th>
<th>Width</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>G_PERIOD</td>
<td>1</td>
<td>time</td>
<td>Clock period.</td>
</tr>
<tr>
<td>G_INITVALUE</td>
<td>1</td>
<td>std_logic</td>
<td>Initial value of the non-inverted clock output.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Port</th>
<th>Width</th>
<th>Direction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>clk_o</td>
<td>1</td>
<td>Output</td>
<td>Non-inverted clock output. Use this output for single ended or differential clocks.</td>
</tr>
<tr>
<td>clk_n_o</td>
<td>1</td>
<td>Output</td>
<td>Inverted clock output. Use if a differential clock is needed, leave open if single-ended clock is needed.</td>
</tr>
<tr>
<td>stop_sim_i</td>
<td>1</td>
<td>Input</td>
<td>When ‘1’, stops the clock. This will normally stop the simulation.</td>
</tr>
</tbody>
</table>