

1. Some theory background.

1.1 Transfer function

$$H(z) = \left(\frac{1 - z^{-rg}}{1 - z^{-1}} \right)^m \quad [1]$$

1.2 Truncation

In interpolation mode truncation not used. Full output data width is:

$$dw_{out} = dw_{max} = dw + \log_2 \left(\frac{r^m}{r} \right)$$

In decimation mode dw_{max} is large for practical cases. Truncation may be used at each stage reducing register widths. See [2] for details.

2. Core description.

2.1 Source files.

- `cic_package.sv` — function set for CIC-decimator register's width calculation
- `comb.sv` — comb module
- `integrator.sv` — integrator module
- `downsampler.sv` — downsampling register module (used in CIC-decimator)
- `cic_i.sv` — parametrizable CIC integrator module
- `cic_d.sv` — parametrizable CIC decimator module
- `cic_i_tb.sv`, `cic_d_tb.sv` — testbench examples
- `cic_i_tb_run.tcl`, `cic_d_tb_run.tcl` — simulation scripts

2.2 Core parameters

- `dw` — input data width for integrator module
- `idw/odw` — input/output data width for integrator module
- `m` — CIC-filter order (m combs + m integrators)
- `r` — interpolation/decimation ratio
- `g` — differential delay in coms

3. Getting started (ModelSim example).

3.1 Setup core

```
mkdir ~/cic_test
```

```
cd ~/cic_test
```

svn co http://opencores.org/ocsvn/cic_core/cic_core

3.2 Create project in ModelSim.

Specify folder (cic_test), add source files from cic_core/trunk/sim and cic_core/trunk/src.

3.3 Run test.

In ModelSim console type «do cic_core/trunk/sim/cic_d_tb_run.tcl» (CIC-decimator example) or «do cic_core/trunk/sim/cic_i_tb_run.tcl» (CIC-interpolator).

[1] <http://www.design-reuse.com/articles/10028/understanding-cascaded-integrator-comb-filters.html>

[2] Hogenauer, E. B., "An Economical Class of Digital Filters for Decimation and Interpolation", IEEE® Transactions on Acoustics, Speech, and Signal Processing, Vol. ASSP-29, No. 2, April 1981, pp. 155-162.