

# Division Algorithms and Hardware Implementations

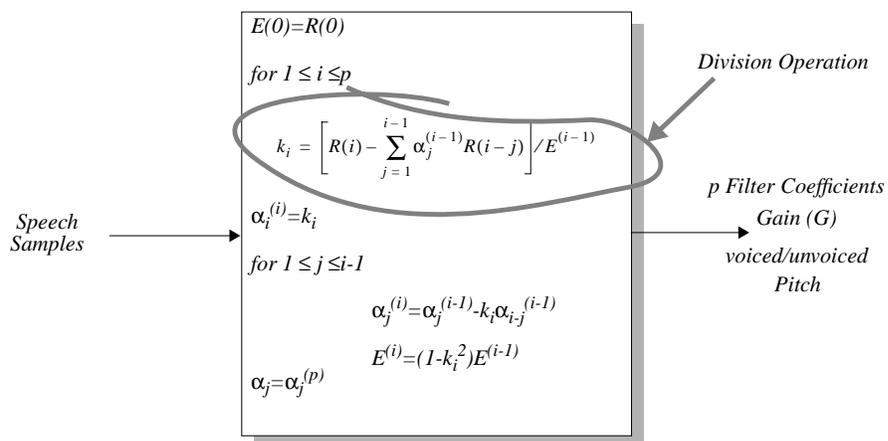
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EE 213A: Advanced DSP Circuit Design

## Motivation

- Implementation of LPC speech coder
- Division operation required in Levinson-Durbin algorithm



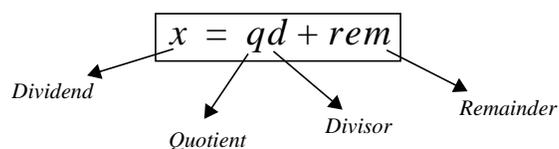
# Basic Division Algorithms

- **Digit Recurrence Algorithm**
  - Restoring Division
  - Non-Restoring Division
  - SRT Division (Sweeney, Robertson, and Tocher)
- **Multiplicative Algorithm**
- **Approximation Algorithms**
- **CORDIC Algorithm**
- **Continued Product Algorithm**

Useful site

<http://www.ecs.umass.edu/ece/koren/arith/simulator>

# Definitions and Notations



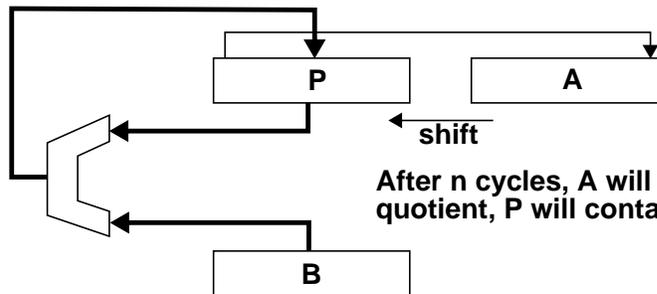
$$|rem| < |d|ulp$$

unit in the last position  
 $ulp=1$  for integer quotient  
 $ulp=r^{-n}$  for radix- $r$  representation  
with  $n$ -digit quotient

- **Two types of division operations**
  - Integer division: with integer operands and result
  - Fractional division: operands and results are fractions
- **Any division algorithm can be carried out independent of**
  - Position of the decimal point
  - sign of operands

# Restoring Division Algorithm

- Put  $x$  in register A,  $d$  in register B,  $0$  in register P, and perform  $n$  divide steps ( $n$  is the quotient wordlength)
- Each step consists of
  - (i) Shift the register pair (P,A) one bit left
  - (ii) Subtract the contents of B from P, put the result back in P
  - (iii) If the result is -ve, set the low-order bit of A to 0 otherwise to 1
  - (iv) If the result is -ve, restore the old value of P by adding the contents of B back in P



After  $n$  cycles, A will contain the quotient, P will contain the remainder

# Restoring Division Example

P	A	Operation
00000	1110	Divide 14 = 1110 by 3 = 11. B register always contains 0011
00001	110	step 1(i): shift
-00011		step 1(ii): subtract
-----		
-00010	1100	step 1(iii): quotient is -ve, set quotient bit to 0
00001	1100	step 1(iv): restore
00011	100	step 2(i): shift
-00011		step 2(ii): subtract
-----		
00000	1001	step 2(iii): quotient is +ve, set quotient bit to 1
00001	001	step 3(i): shift
-00011		step 3(ii): subtract
-----		
-00010	0010	step 3(iii): quotient is -ve, set quotient bit to 0
00001	0010	step 3(iv): restore
00010	010	step 4(i): shift
-00011		step 4(ii): subtract
-----		
-00001	0100	step 4(iii): quotient is -ve, set quotient bit to 0
00010	0100	step 4(iv): restore

- The quotient is 0100 and the remainder is 00010
- The name *restoring* because if subtraction by  $b$  yields a negative result, the  $P$  register is restored by adding  $b$  back

# Non-Restoring Division Algorithm

- A variant that skips the restoring step and instead works with negative residuals
- If P is negative
  - (i-a) Shift the register pair (P,A) one bit left
  - (ii-a) Add the contents of register B to P
- If P is positive
  - (i-b) Shift the register pair (P,A) one bit left
  - (ii-b) Subtract the contents of register B from P
- (iii) If P is negative, set the low-order bit of A to 0, otherwise set it to 1
- After n cycles
  - The quotient is in A
  - If P is positive, it is the remainder, otherwise it has to be restored (add B to it) to get the remainder

# Non-Restoring Division Example

P	A	Operation
00000	1110	Divide 14 = 1110 by 3 = 11. B register always contains 0011 step 1(i-b): shift step 1(ii-b): subtract b (add two's complement)
00001	110	
+00011		
-----		
11110	1100	step 1(iii): P is negative, so set quotient bit to 0 step 2(i-a): shift step 2(ii-a): add b
11101	100	
+00011		
-----		
00000	1001	step 2(iii): P is +ve, so set quotient bit to 1 step 3(i-b): shift step 3(ii-b): subtract b
00001	001	
+11101		
-----		
11110	0010	step 3(iii): P is -ve, so set quotient bit to 0 step 4(i-a): shift step 4(ii-a): add b
11100	010	
+00011		
-----		
11111	0100	step 4(iii): P is -ve, set quotient bit to 0 Remainder is negative, so do final restore step
+00011		
-----		
00010		

- The quotient is 0100 and the remainder is 00010
- *restoring* division seems to be more complicated since it involves extra addition in step (iv)
- This is not true since the sign resulting from the subtraction is tested at adder o/p and only if the sum is +ve, it is loaded back to the P register

# SRT Division Algorithm

- Pre-normalization of divisor ( $1/2 \leq d \leq 1$ ) and dividend ( $x < d$ )

*For an  $n$ -bit quotient,  $n$  iterations are needed  
Each iteration involves 4 intermediate steps*

*Start by defining a residual (or partial remainder)  $w$  and setting  $w[0]=x$*

*step1: One digit left-shift of  $w[j]$  to produce  $rw[j]$*

*step2: Determine the quotient  $q_{j+1}$  using quotient-digit select function*

$$q_{j+1} = \text{SEL}(w[j], d)$$

*step3: Generation of  $d q_{j+1}$*

*step4: Generation of  $w[j+1] = rw[j] - d q_{j+1}$*

# Quotient-digit Select Function

- The Quotient-digit set plays a crucial role in the complexity of implementation
- Restoring algorithm  $\Rightarrow 0 \leq q_j \leq r-1$
- Non-Restoring algorithm  $\Rightarrow q_j \in \{-1, 1\}$
- SRT quotient-digit selection function

$$q_{j+1} = \begin{bmatrix} 1 & 1/2 \leq 2w[j] \\ 0 & -1/2 \leq 2w[j] < 1/2 \\ -1 & 2w[j] < -1/2 \end{bmatrix}$$

- SRT division is very fast in the case of consecutive zeroes in  $q$  ( $w[j+1] = rw[j] - d q_{j+1} = rw[j]$ )

# SRT Division Example

- Example  $d=0.1101$ ,  $x=0.011000$

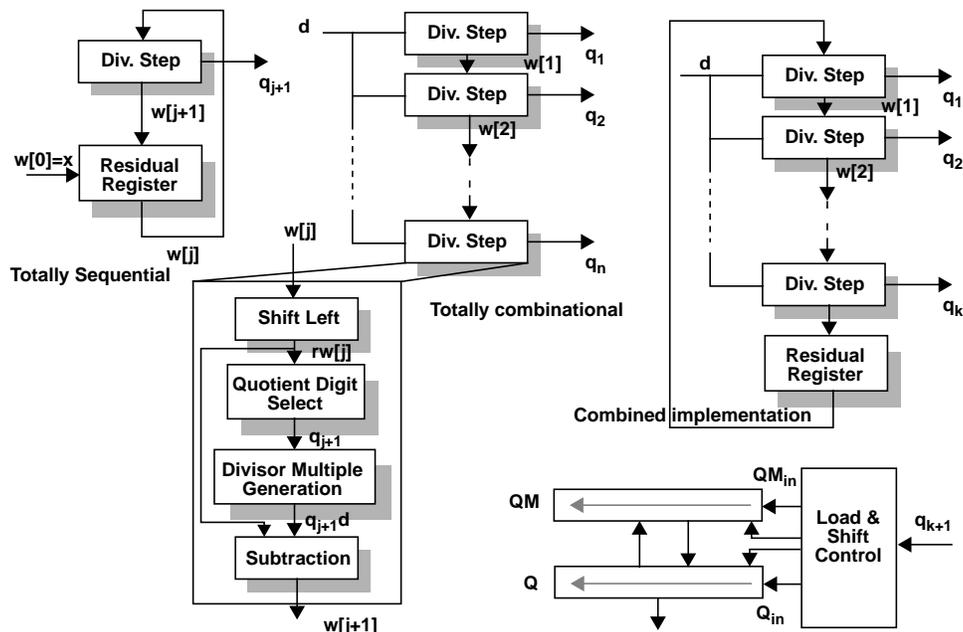
Table 1: Example of radix-2 SRT Division

j	$2w[j]$	$q_{j+1}$	$Q[j]$	$QM[j]$
0	0.110000	1	0	0
1	1.111000	0	0.1	0.0
2	1.110000	0	0.10	0.01
3	1.100000	0	0.100	0.011
4	1.000000	-1	0.1000	0.0111
5	1.101000	0	0.01111	0.01110
6	1.010000	-1	0.011110	0.011101

- Quotient Conversion (on-the-fly conversion algorithm) with initial conditions  $Q[0]=QM[0]=0$

$$Q[k+1] = \begin{cases} Q[k] + q_{k+1}r^{-(k+1)} & q_{k+1} \geq 0 \\ QM[k] + (r - |q_{k+1}|)r^{-(k+1)} & q_{k+1} < 0 \end{cases} \quad QM[k+1] = \begin{cases} Q[k] + (q_{k+1} - 1)r^{-(k+1)} & q_{k+1} > 0 \\ QM[k] + ((r-1) - |q_{k+1}|)r^{-(k+1)} & q_{k+1} \leq 0 \end{cases}$$

# SRT Division Implementation



## References

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- **Stuart F. Oberman, and Michael J. Flynn, “Division Algorithms and Implementations ,” IEEE Transactions on Computers, vol. 46, no. 8, August 1997.**
- **“Computer Arithmetic: A Quantitative Approach” by John L. Hennessey & David P. Patterson, Second Edition**
- **COMS 252A Course Notes “ Digital Arithmetic ”, Professor Ercegovac**